

# IEEE ICMA 2020 Final Technical Program

Session	Session Title	Paper 1	Paper 2	Paper 3	Paper 4	Paper 5	Paper 6	Date	Beijing Time (UTC+8)
WP1-1	Intelligent Biomedical Instrument Technology	231801	234321	232381	234281	230881	231351	Oct.14	13:30 - 15:00
WP2-1	Robot Navigation and Control Algorithm (I)	231101	233041	233581	231061	233021	233091	Oct.14	15:15 - 16:45
WP3-1	Robot Navigation and Control Algorithm (II)	231401	230781	231171	231041	232561	233081	Oct.14	17:00 - 18:30
WP1-2	Intelligent Mechatronics and Application	231451	234011	230641	233321	230241	230371	Oct.14	13:30 - 15:00
WP2-2	Manipulator Control and Manipulation (I)	233791	233341	231081	233671	230051	232121	Oct.14	15:15 - 16:45
WP3-2	Manipulator Control and Manipulation (II)	233491	231551	231641	220951	233691	233051	Oct.14	17:00 - 18:30
WP1-3	Industrial, Manufacturing Process and Automation (I)	232421	233611	231001	230381	231721	232301	Oct.14	13:30 - 15:00
WP2-3	Industrial, Manufacturing Process and Automation (II)	232582	230891	230673	232771	233811	231051	Oct.14	15:15 - 16:45
WP3-3	Industrial, Manufacturing Process and Automation (III)	233161	231461	231371	232141	234521	232391	Oct.14	17:00 - 18:30
WP1-4	Vision System, Robotic Vision (I)	230681	231211	231311	231062	232051	233881	Oct.14	13:30 - 15:00
WP2-4	Vision System, Robotic Vision (II)	233111	232711	232661	230672	230711	233401	Oct.14	15:15 - 16:45
WP3-4	Micro and Nano Systems	226931	233701	220781	231961	230091	232891	Oct.14	17:00 - 18:30
WP1-5	Space Robotics and Mechatronics	232031	232821	230971	233921	232471	234441	Oct.14	13:30 - 15:00
WP2-5	Elements, Structures, and Mechanisms (I)	232701	232311	232241	231671	232741	232742	Oct.14	15:15 - 16:45
WP3-5	Elements, Structures, and Mechanisms (II)	231951	233821	231981	232511	231191	231192	Oct.14	17:00 - 18:30
WP1-6	Biomimetic Underwater Robots	232361	234421	232041	233411	233291	231691	Oct.14	13:30 - 15:00
WP2-6	Biomimetic Measurement and Control in Robotics	233101	233031	231841	231842	225861	232721	Oct.14	15:15 - 16:45
WP3-6	Biomimetic Systems	231431	234001	232921	231701	233011	232831	Oct.14	17:00 - 18:30
TA1-1	Control Theory and Application (I)	230441	230861	232743	233501	233441	233651	Oct.15	9:30 - 11:00
TA2-1	Control Theory and Application (II)	230922	231151	232601	232491			Oct.15	11:15 - 12:15
TP1-1	Control Theory and Application (III)	233421	231654	233431	230331	233781	232392	Oct.15	13:30 - 15:00
TP2-1	Control Theory and Application (IV)	232101	230621	230941	233711	230981	230791	Oct.15	15:30 - 17:00
TA1-2	Signal and Image Processing (I)	232021	231181	230671	231881	231031	231811	Oct.15	9:30 - 11:00
TA2-2	Signal and Image Processing (II)	230901	231541	234551	234571			Oct.15	11:15 - 12:15
TP1-2	Signal and Image Processing (III)	230431	233371	230701	232161	231141	231723	Oct.15	13:30 - 15:00
TP2-2	Signal and Image Processing (IV)	233641	234111	231861	233241	230561	230651	Oct.15	15:30 - 17:00
TA1-3	Mobile Robot System (I)	226921	231281	233951	230521	230601	230511	Oct.15	9:30 - 11:00
TA2-3	Mobile Robot System (II)	231341	230351	233571	233831			Oct.15	11:15 - 12:15
TP1-3	Mobile Robot System (III)	226911	231731	234141	231501	232801	230991	Oct.15	13:30 - 15:00
TP2-3	Mobile Robot System (IV)	231331	231321	234131	230962	231761	232851	Oct.15	15:30 - 17:00
TA1-4	Modeling, Simulation Techniques and Methodologies (I)	230911	231621	234251	231441	232271	232064	Oct.15	9:30 - 11:00

TA2-4	Modeling, Simulation Techniques and Methodologies (II)	233181	232321	230951	232071			Oct.15	11:15 - 12:15
TP1-4	Modeling, Simulation Techniques and Methodologies (III)	231421	233471	231472	231473	233911	233851	Oct.15	13:30 - 15:00
TP2-4	Modeling, Simulation Techniques and Methodologies (IV)	230231	233121	234381	231471	231571	230141	Oct.15	15:30 - 17:00
TA1-5	Cognitive Science and Neural Engineering Methods (I)	233731	233941	233531	230491	231871	231872	Oct.15	9:30 - 11:00
TA2-5	Cognitive Science and Neural Engineering Methods (II)	231491	234081	233741	232431			Oct.15	11:15 - 12:15
TP1-5	Cognitive Science and Neural Engineering Methods (III)	230121	231751	233171	231821	233551	233841	Oct.15	13:30 - 15:00
TP2-5	Cognitive Science and Neural Engineering Methods (IV)	233001	231651	231652	231653	231201	232441	Oct.15	15:30 - 17:00
TA1-6	Medical, Biomedical and Rehabilitation Systems (I)	234091	230001	230013	234301	230761		Oct.15	9:30 - 11:00
TA2-6	Medical, Biomedical and Rehabilitation Systems (II)	231631	231711	230211	233991			Oct.15	11:15 - 12:15
TP1-6	Medical Robots for Minimal Invasive Surgery (I)	231231	231221	232251	232221	231582	231482	Oct.15	13:30 - 15:00
TP2-6	Medical Robots for Minimal Invasive Surgery (II)	226901	231511	231241	230691	231271	230571	Oct.15	15:30 - 17:00
FA1-1	Neuro, Fuzzy, and Intelligent Control (I)	230151	230531	232061	234531	234541	234561	Oct.16	8:30 - 10:00
FA2-1	Neuro, Fuzzy, and Intelligent Control (II)	231251	233871	234261	234241	233661	232592	Oct.16	10:30 - 12:00
FA1-2	Surgical Robot System	231261	231262	231263	231264	234151	231941	Oct.16	8:30 - 10:00
FA2-2	Soft Robotics	230871	230382	234311	234351	231532	233151	Oct.16	10:30 - 12:00
FA1-3	Digital Design and Manufacture	233211	231381	232671	231361	233982	233231	Oct.16	8:30 - 10:00
FA2-3	Sensor Networks, Distributed Sensor Systems	233271	233511	234181	230361	233481	233512	Oct.16	10:30 - 12:00
FA1-4	Humanoid Robots	230801	232001	234331	234341	232081	232641	Oct.16	8:30 - 10:00
FA2-4	Human-System Interaction and Interface	233351	234411	234101	233761	233391	230963	Oct.16	10:30 - 12:00
FA1-5	Rotor Dynamics, Vibration Analysis and Vibration Control	231611	231991	232231	232761	233521	233981	Oct.16	8:30 - 10:00
FA2-5	Control Theory and Application (V)	234581	234591	230961	234491			Oct.16	10:30 - 12:00
WA1-P	Poster Session (Intelligent Mechatronics and Automation)	220131	226891	230031	230171	230501	230731	Oct.14	11:00-12:00
		230841	231091	231092	231521	231592	231722		
		231741	231971	232062	232063	232191	232281		
		232521	232571	232621	232631	232901	232911		
		232951	232961	232971	232991	233191	233311		
		233451	233601	233621	233721	233751	233801		
		233891	233973	234191	234201	234221	234291		

\*Yellow background: No Registration Confirm